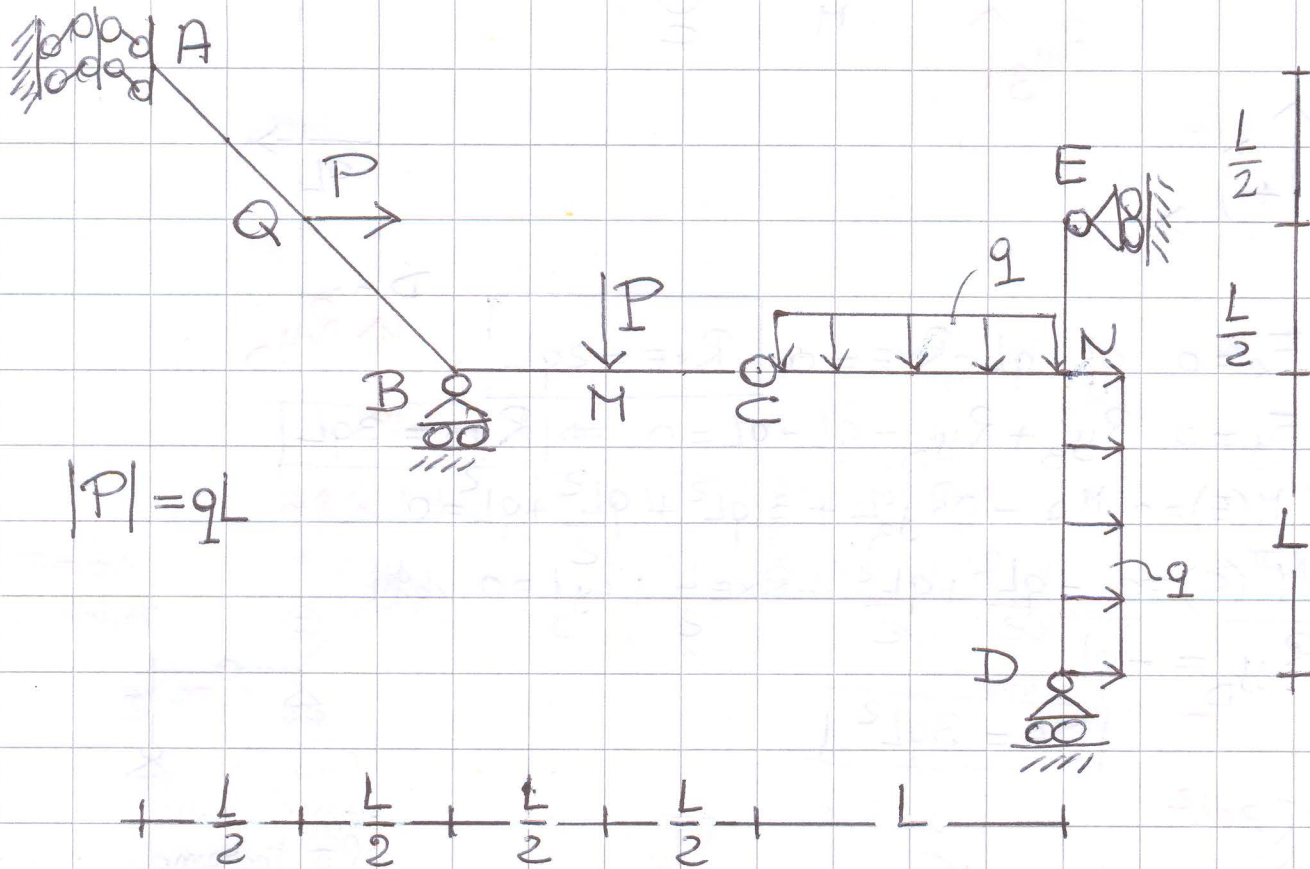


Test in itinere dell'8-5-2013

1

Corsi di Statica A-B; CdL Arch., PROF: AURORA PISANO

ES#1 Determinare le Reazioni Vincolari (RV), le funzioni caratteristiche di sollecitazione (CS) e i relativi diagrammi per la struttura seguente:

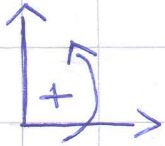
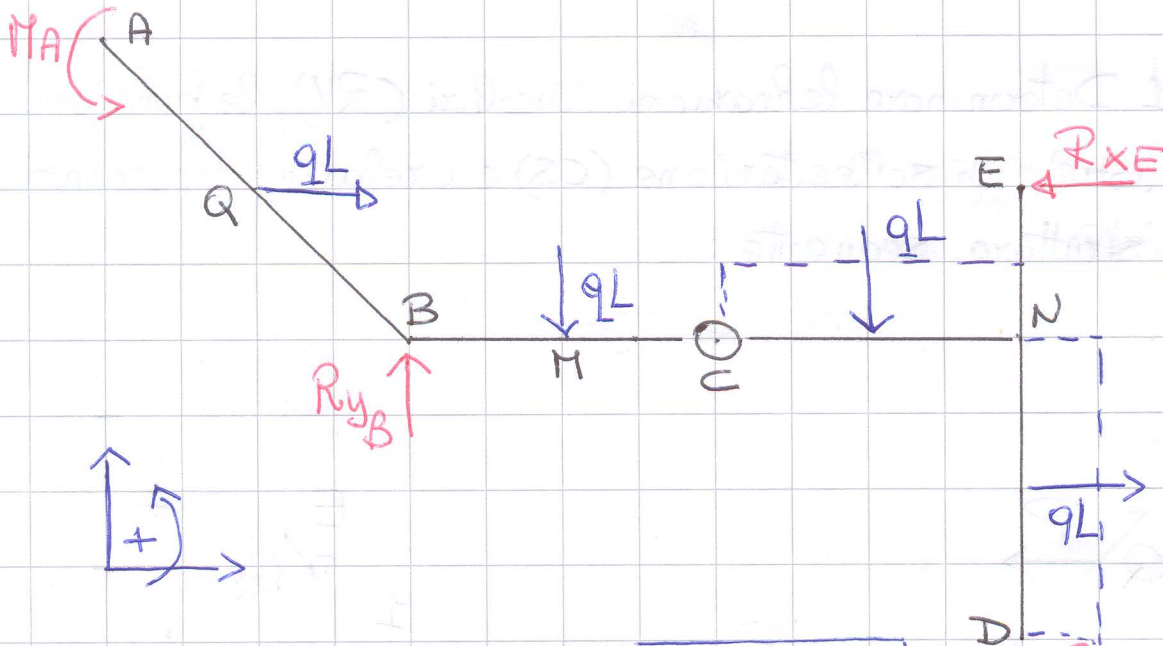


ES#2 Con riferimento alla struttura isostatica dell'ES#1 determinare le reazioni vincolari M_A ed R_{xc} tramite le condizioni di equilibrio dei membri.

SOLUZIONE ES#1

1

Calcolo delle RV - metodo analitico



$$\sum F_x = 0 \quad qL + qL - R_{xE} = 0 \quad \boxed{R_{xE} = 2qL}$$

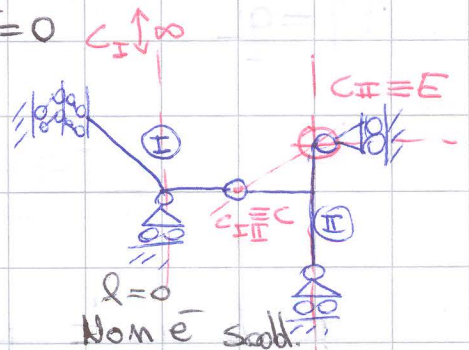
$$\sum F_y = 0 \quad R_{yB} + R_{yD} - qL - qL = 0 \Rightarrow \boxed{R_{yB} = 3qL}$$

$$\sum M(E) = 0 \quad M_A - 2R_{yB}L + \frac{3}{2}qL^2 + \frac{qL^2}{2} + qL^2 = 0$$

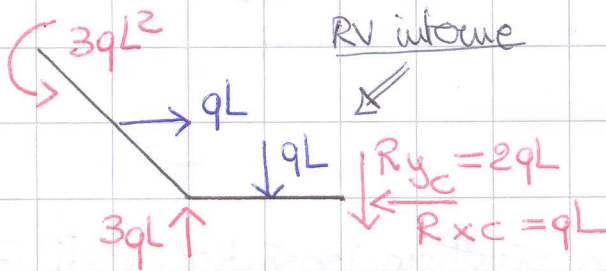
$$\sum M^{\text{II}}(C) = 0 \quad -\frac{qL^2}{2} + \frac{qL^2}{2} + R_{xE}\frac{L}{2} + R_{yD}L = 0$$

$$\boxed{R_{yD} = -qL}$$

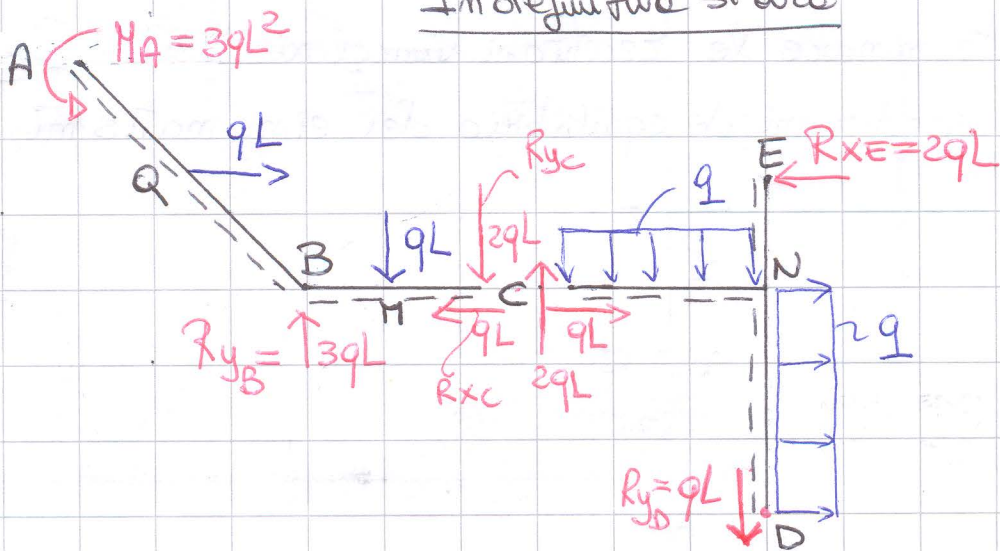
$$\boxed{M_A = 3qL^2}$$



$q=0$
Non è soddisf.
il II teorema delle catene cinematiche

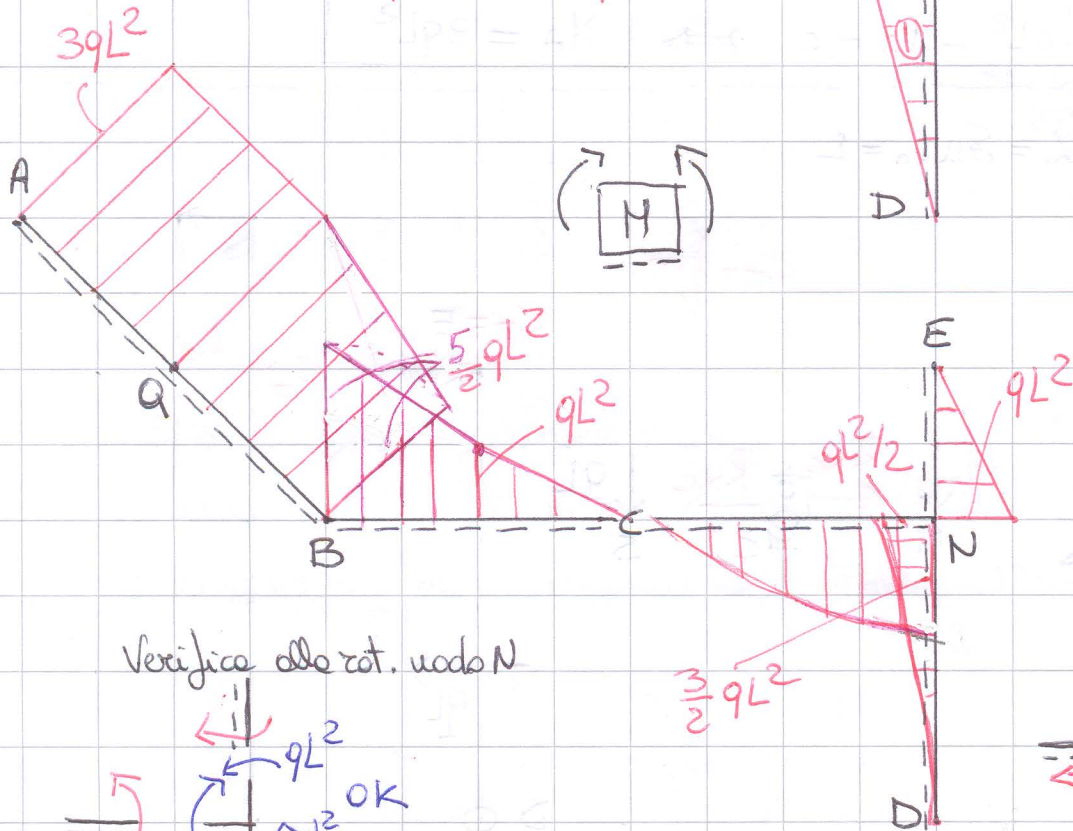
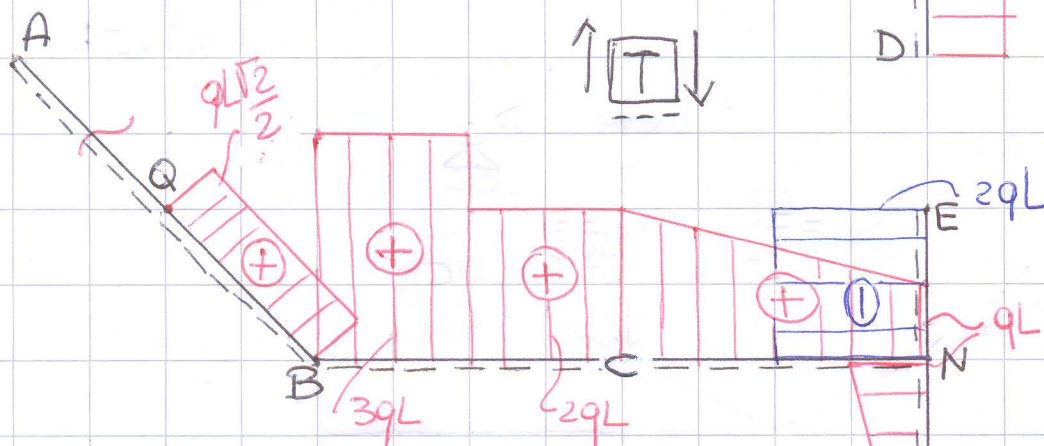
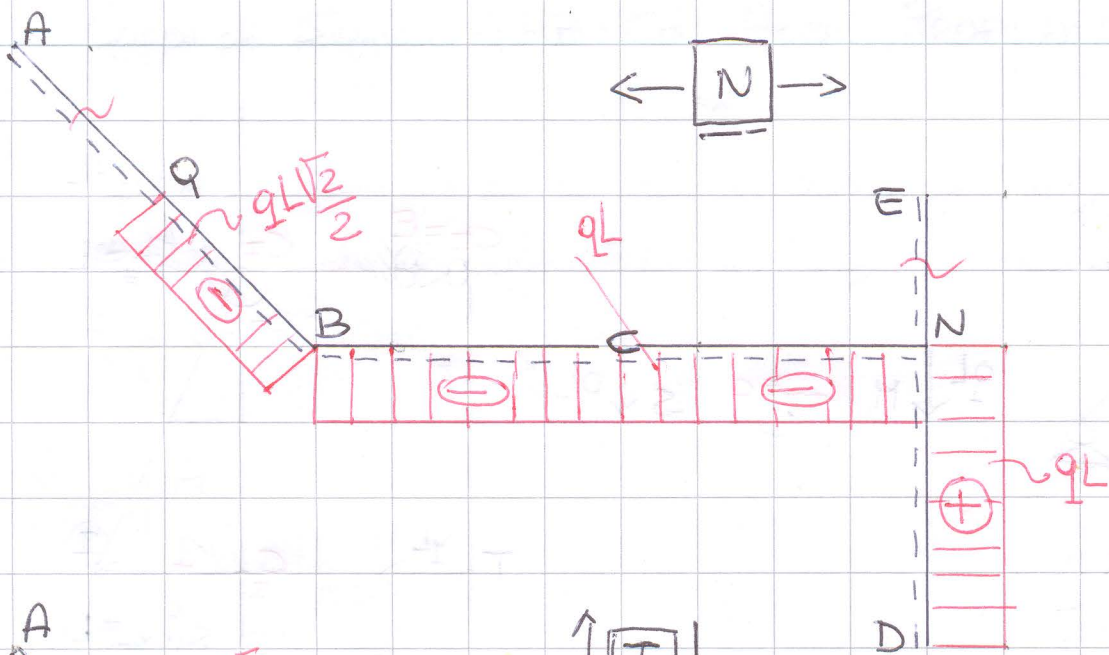


Indefinitiva si trova

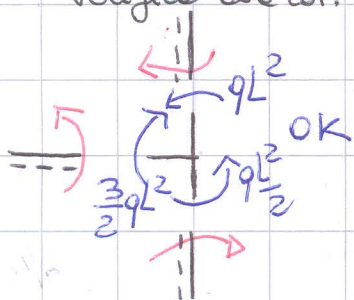


Diagrammi CS

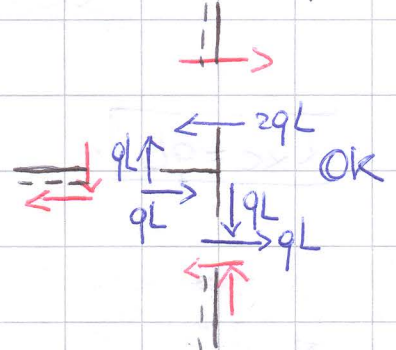
1



Verifica alle rot. nodo N



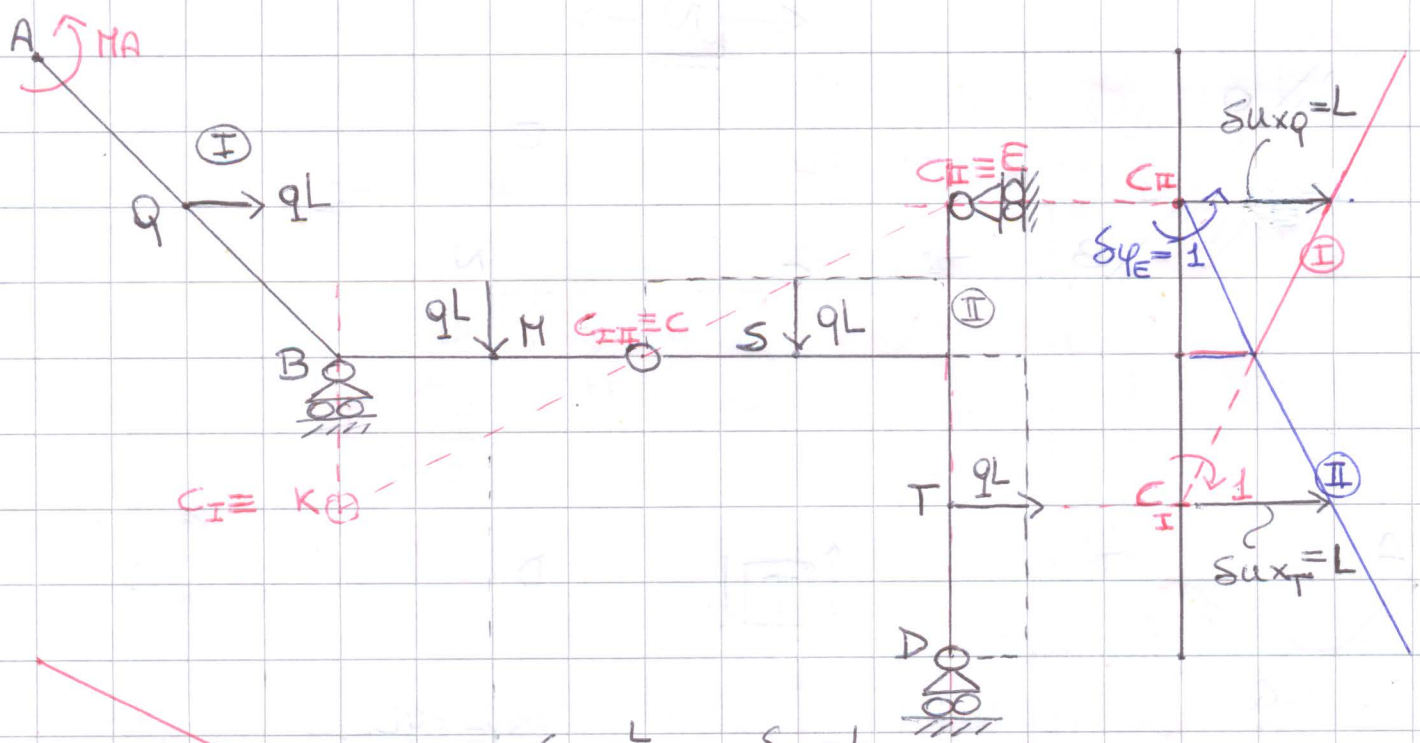
Verifica alle trasl. nodo triplo N



SOLUZIONE ES#2

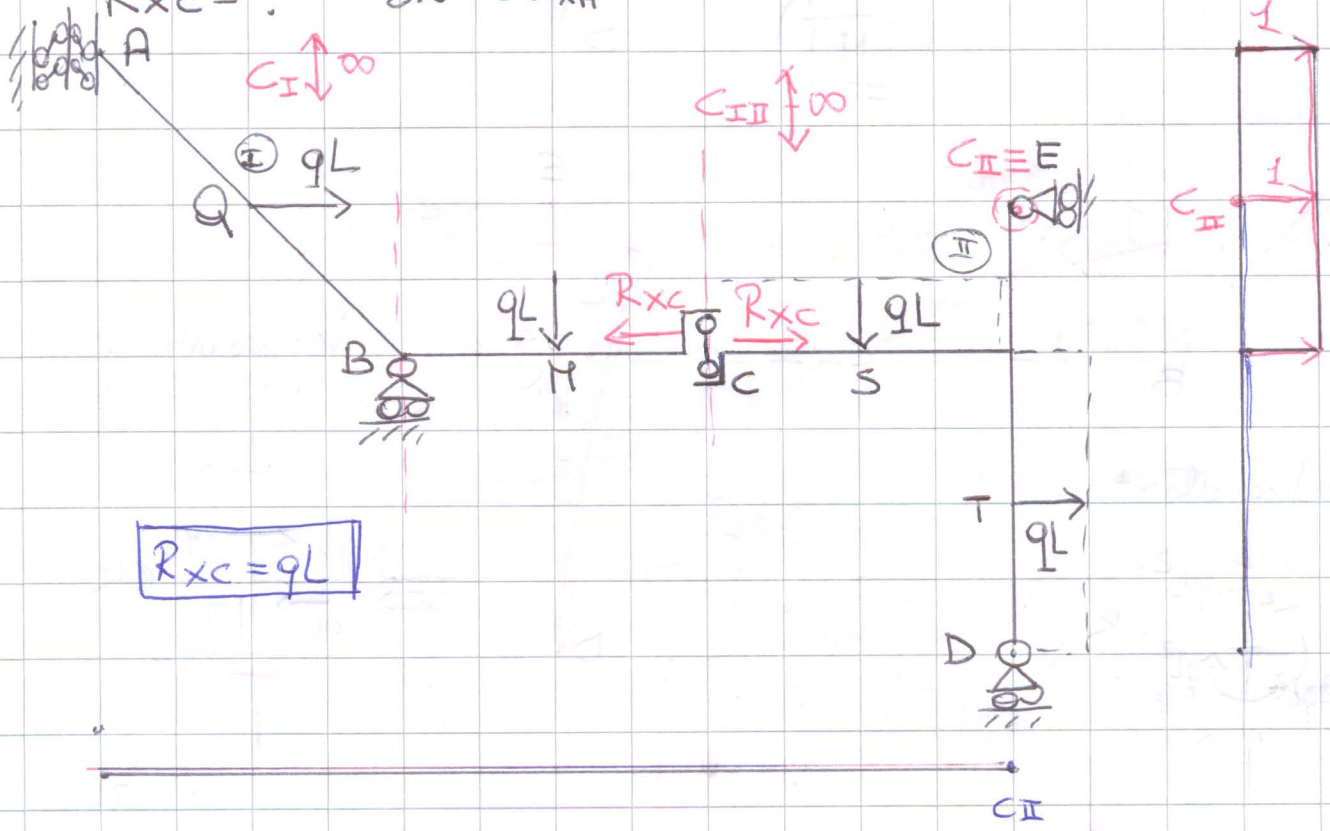
$M_A = ? \quad \delta h = \delta \varphi_E = 1$

1



$$qL^2 + \frac{qL^2}{2} + \frac{qL^2}{2} + qL^2 - M_A = 0 \implies M_A = 3qL^2$$

$R_{xc} = ? \quad \delta h = \delta u_{xA} = 1$



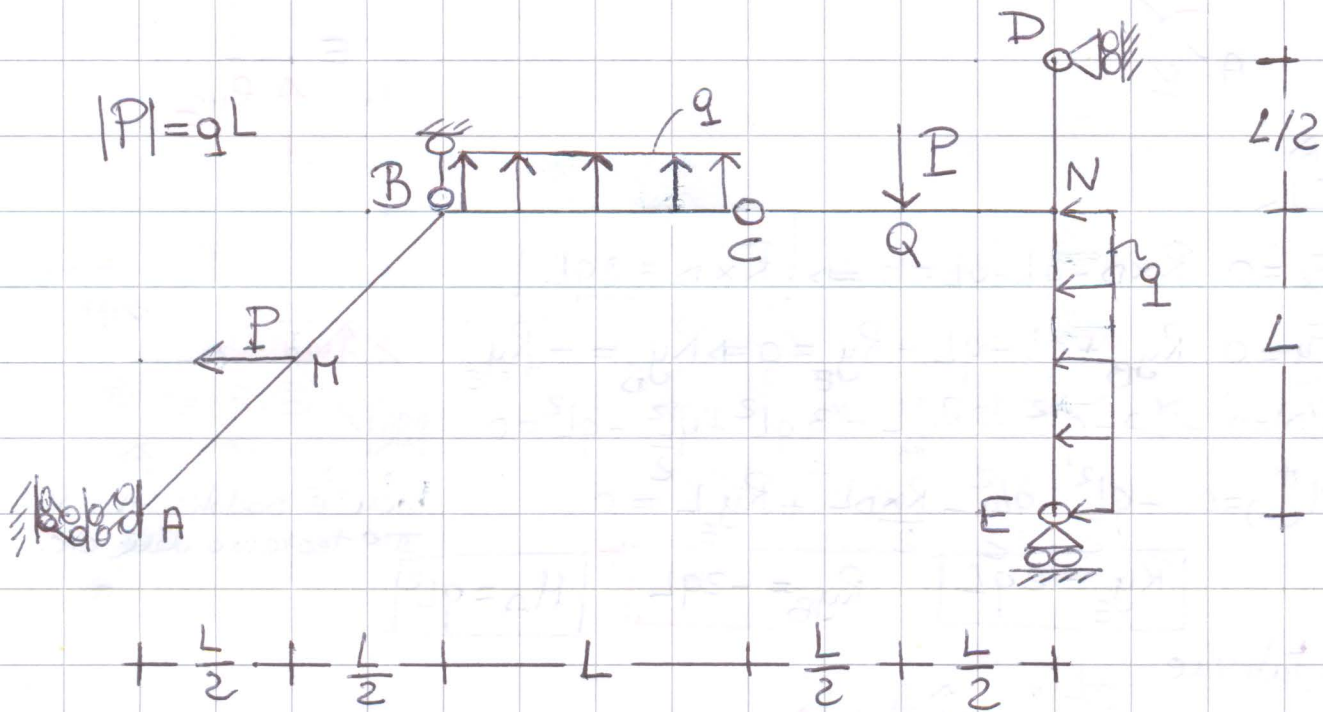
$R_{xc} = qL$

Test in itinere dell'8-5-2013

2

Corsi di Statica A-B; CdL Arch; PROF. AURORA PISANO

ES#1 Determinare le reazioni vincolari (RV), le funzioni caratteristiche di sollecitazione (CS) e i relativi diagrammi per la struttura seguente:

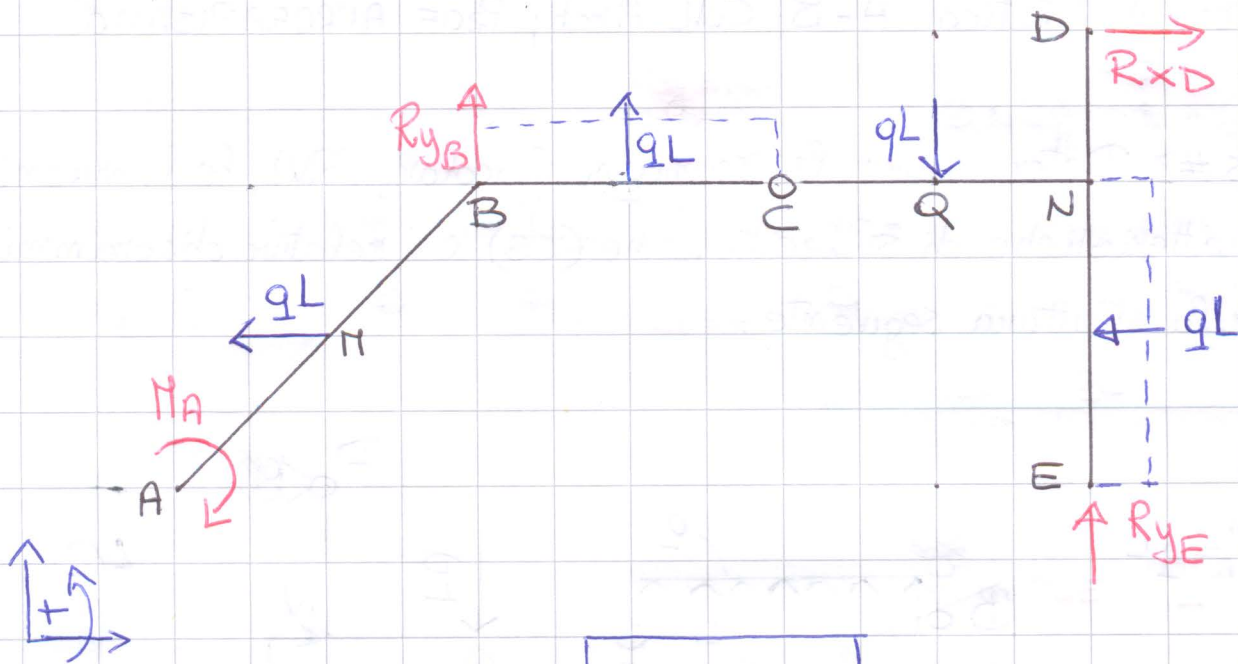


ES#2 Con riferimento alla struttura isostatica dell'ES#1 determinare le reazioni vincolari R_{yE} ed R_{yC} tramite le condizioni di equilibrio dei cinematicismi.

SOLUZIONE ES#1

- Calcolo delle RV - metodo analitico

2



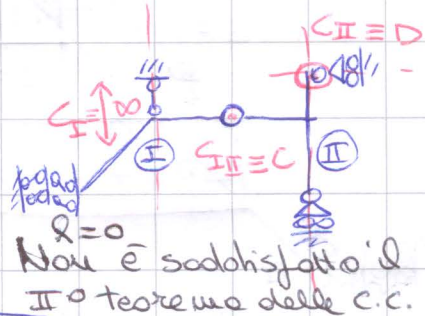
$$\sum F_x = 0 \quad R_{xD} - qL - qL = 0 \Rightarrow R_{xD} = 2qL$$

$$\sum F_y = 0 \quad R_{yB} + qL - qL + R_{yE} = 0 \Rightarrow R_{yB} = -R_{yE}$$

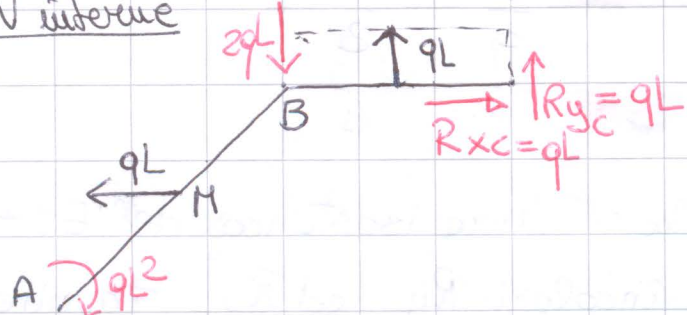
$$\sum M(D) = 0 \quad -M_A - qL^2 - 2R_{yB}L - \frac{3}{2}qL^2 + qL^2 - qL^2 = 0$$

$$\sum M(C) = 0 \quad -\frac{qL^2}{2} - \frac{qL^2}{2} - \frac{R_{xD}L}{2} + R_{yE}L = 0$$

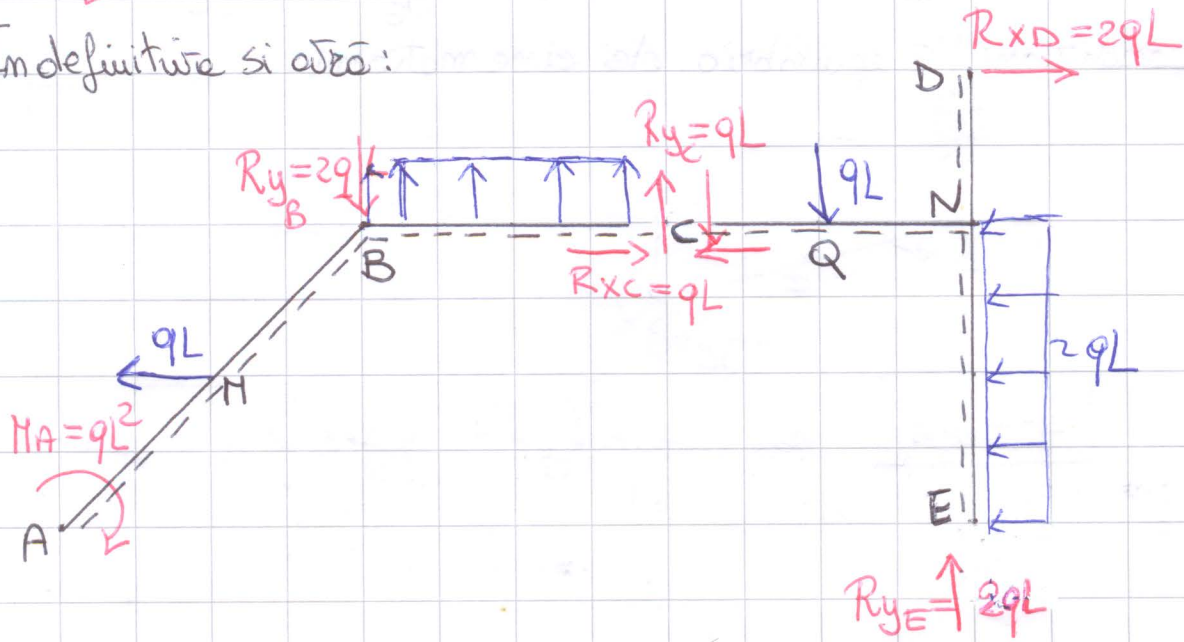
$$R_{yE} = 2qL \quad R_{yB} = -2qL \quad M_A = qL^2$$



RV interne

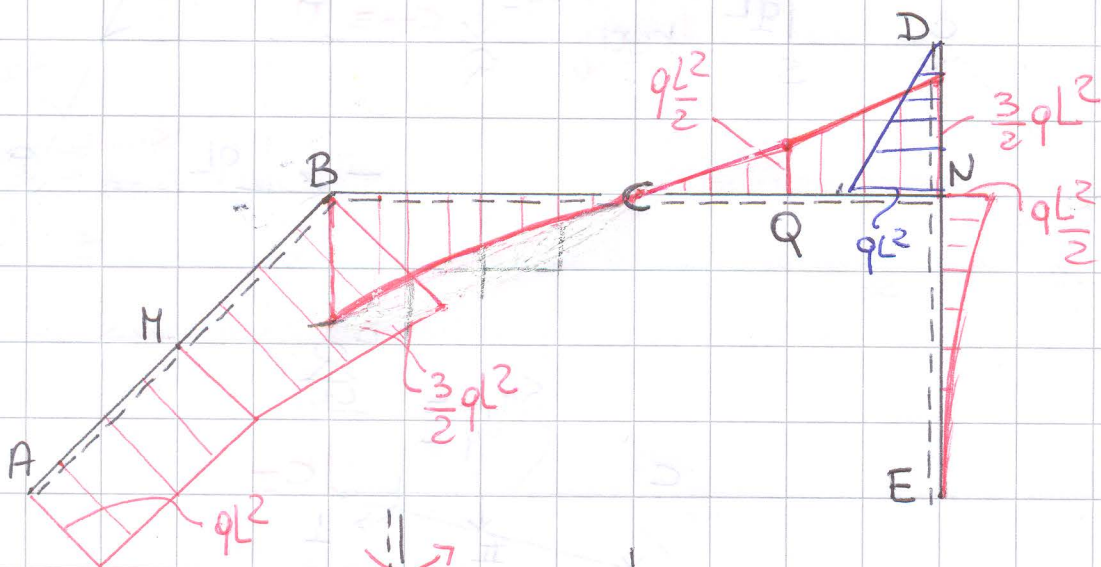
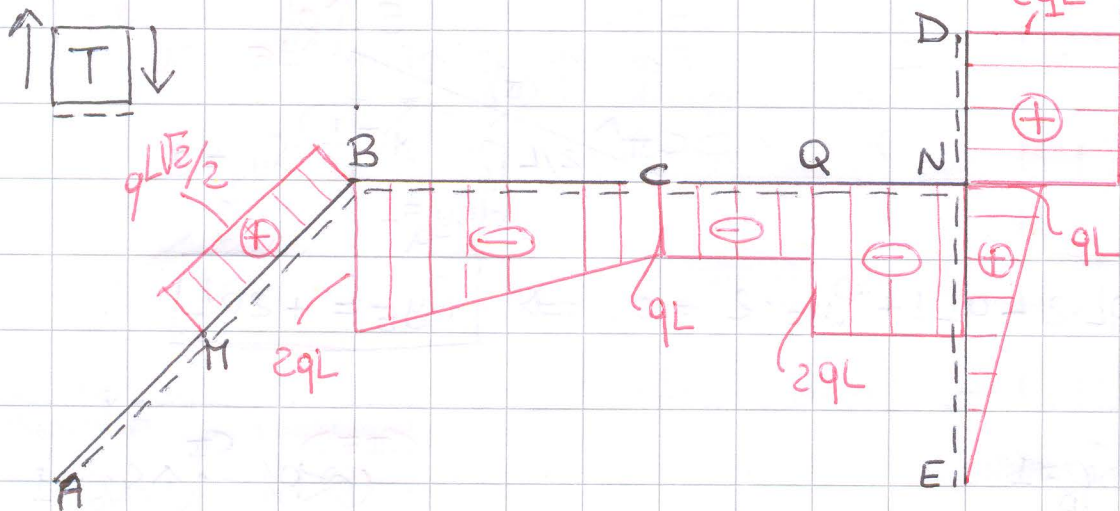
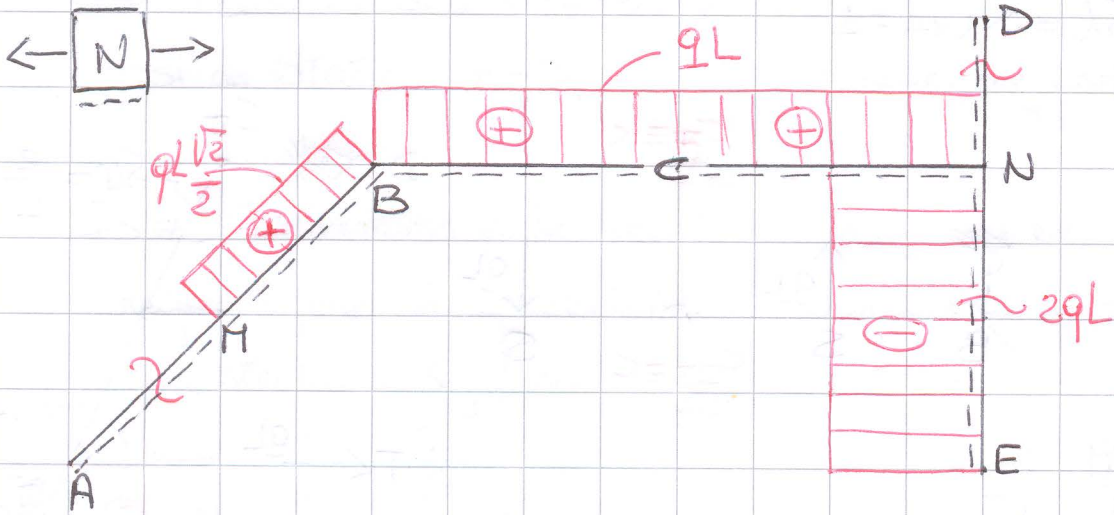


Imdefinitive si avrà:

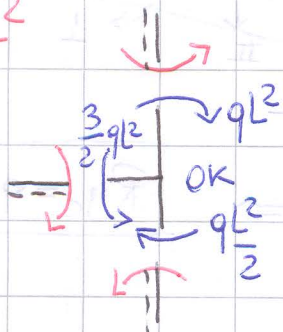


Diagrammi CS

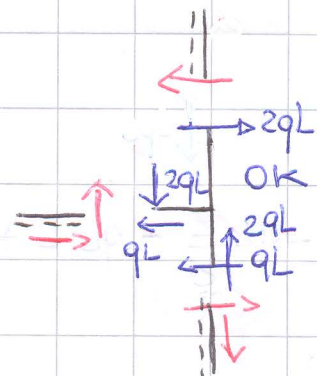
2



Equilibrio alle rotazione nodo N



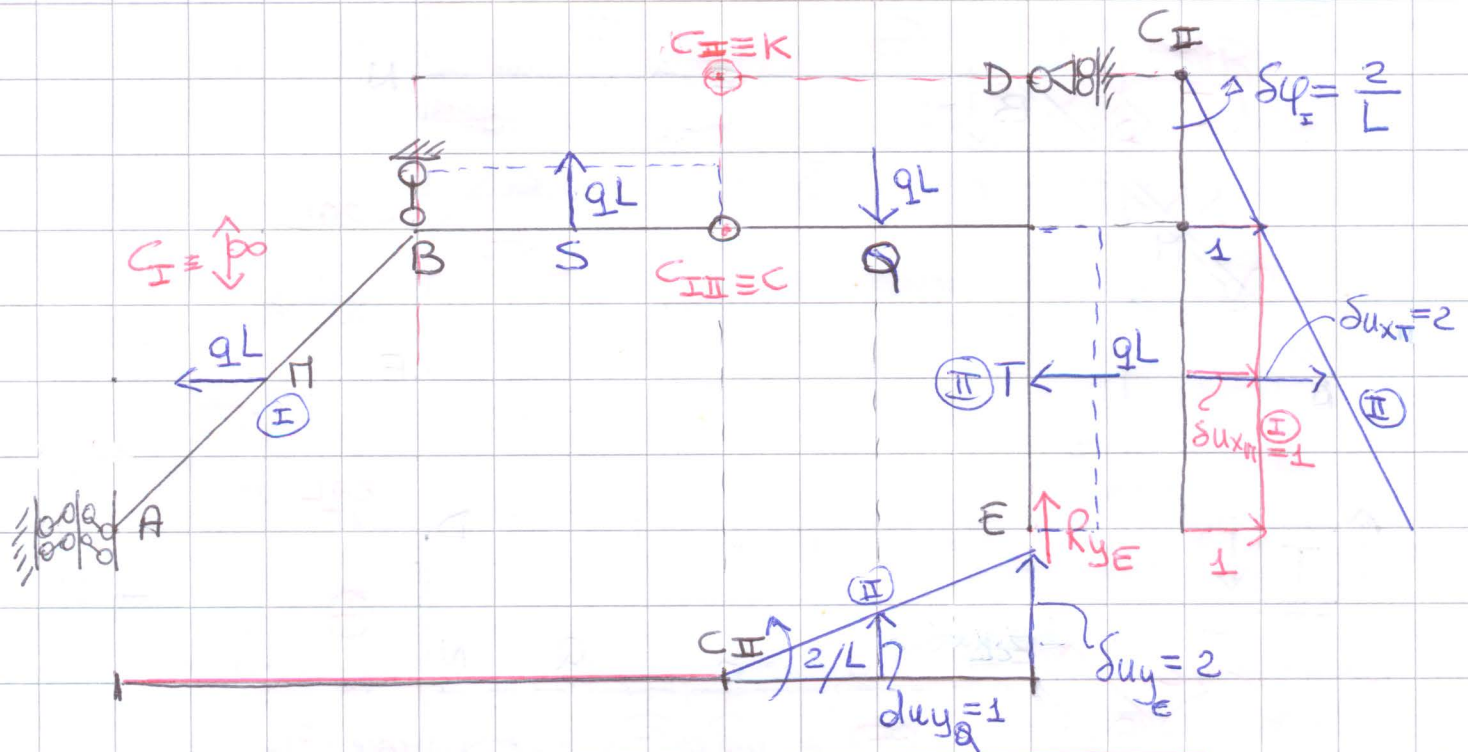
Equilibrio alle trasl. nodo N



SOLUZIONE ES# 2

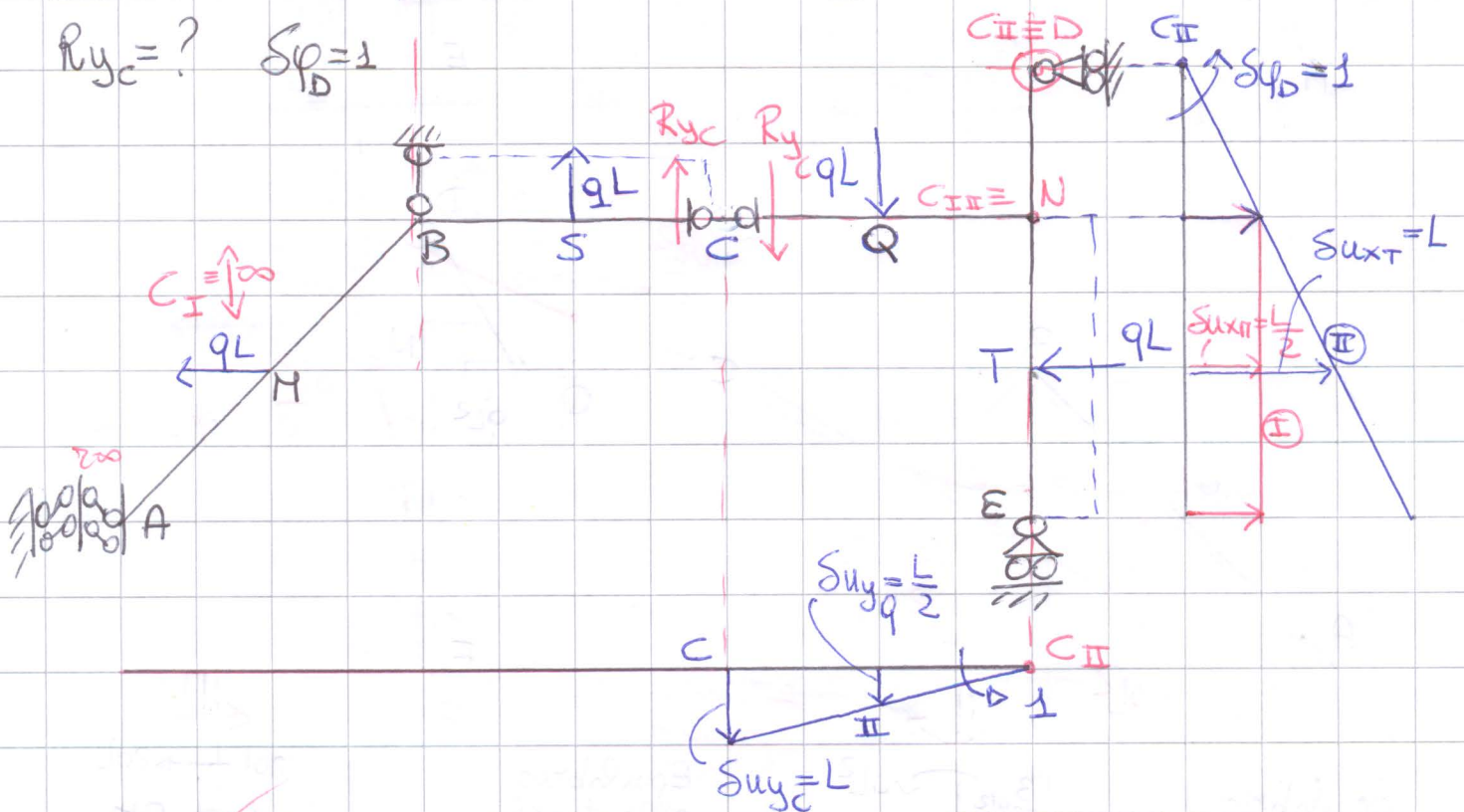
2

$R_{yE} = ? \quad S_h = S_{uxA} = 1$



$-qL \cdot 1 - qL \cdot 2 - qL \cdot 1 + R_{yE} \cdot 2 = 0 \Rightarrow R_{yE} = +2qL$

$R_{yC} = ? \quad S_p = 1$



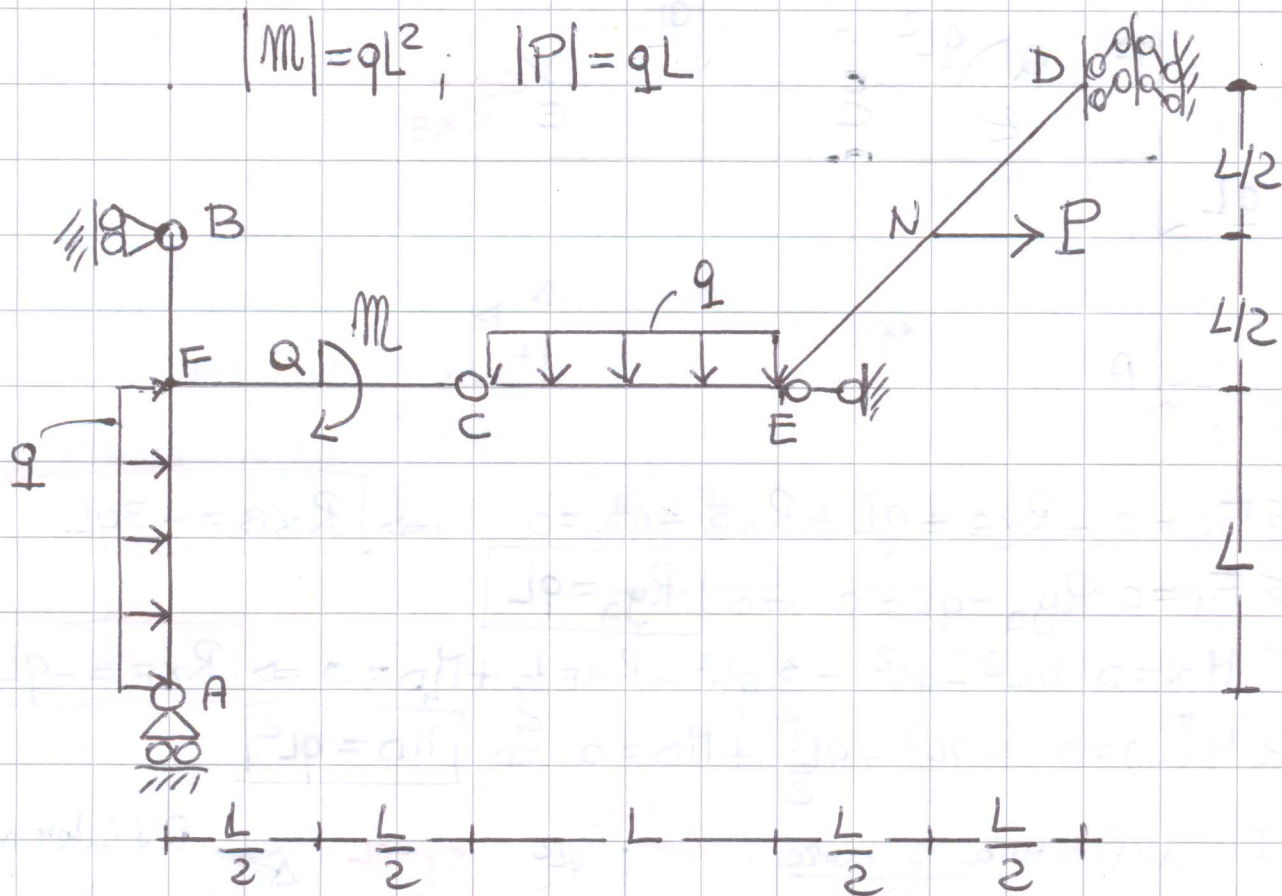
$-qL \cdot \frac{L}{2} - qL \cdot L + qL \cdot \frac{L}{2} + R_{yC} L = 0 \Rightarrow R_{yC} = qL$

Test in itinere dell' 8-5-2013

3

Corsi di Statica A-B; CdL Arch; Prof: AURORA PISANO

Es #1 Determinare le reazioni vincolari (RV), le funzioni caratteristiche di sollecitazione (ES) e i relativi diagrammi per la struttura seguente:

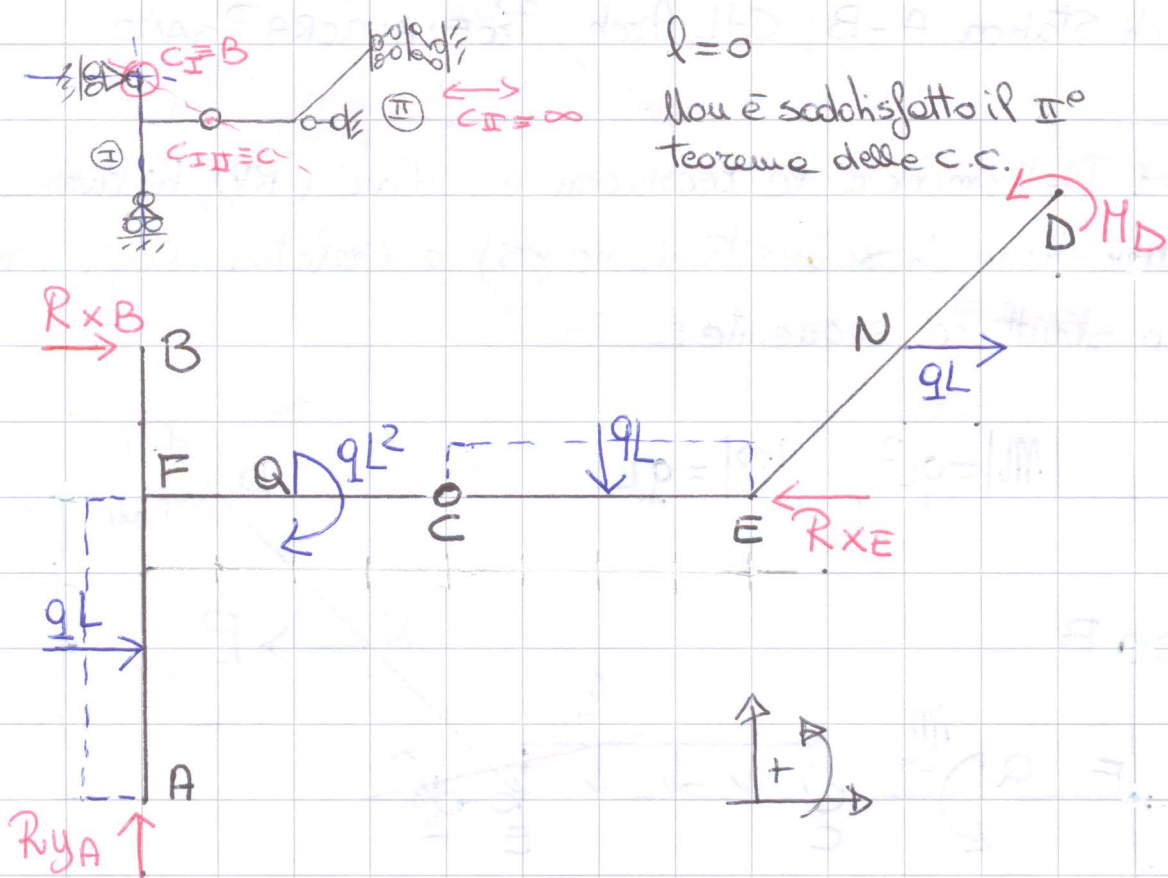


Es #2 Con riferimento alla struttura isostatica dell' ES #1 determinare le reazioni vincolari R_{XE} ed R_{XC} tramite le condizioni di equilibrio dei cinematicismi.

SOLUZIONE ES #1

Calcolo delle RV - metodo analitico

3



$l=0$
 Non è soddisfatto il II° teorema delle c.c.

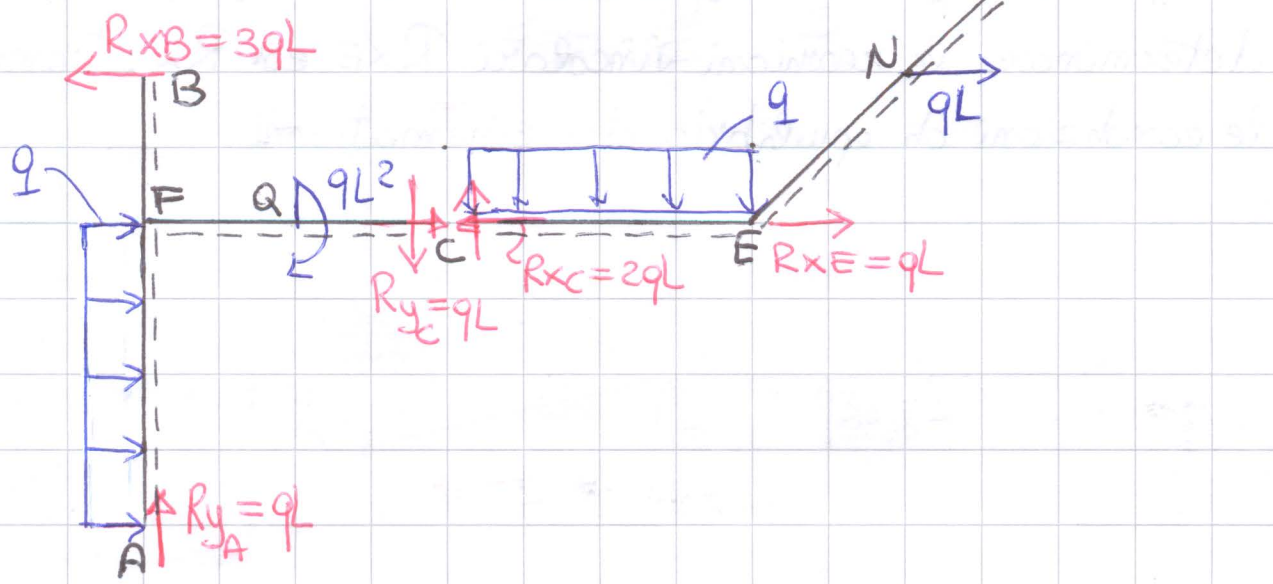
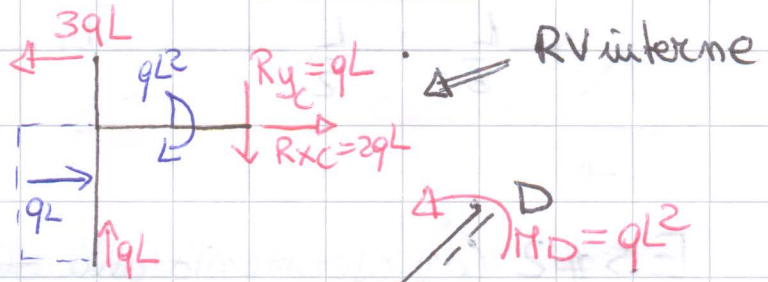
$$\sum F_x = 0 \Rightarrow -R_{xE} + qL + R_{xB} + qL = 0 \Rightarrow R_{xB} = -3qL^*$$

$$\sum F_y = 0 \Rightarrow R_{yA} - qL = 0 \Rightarrow R_{yA} = qL$$

$$\sum M_B = 0 \Rightarrow qL^2 - qL^2 - \frac{3}{2}qL^2 - R_{xE} \frac{L}{2} + M_D = 0 \Rightarrow R_{xE} = -qL^*$$

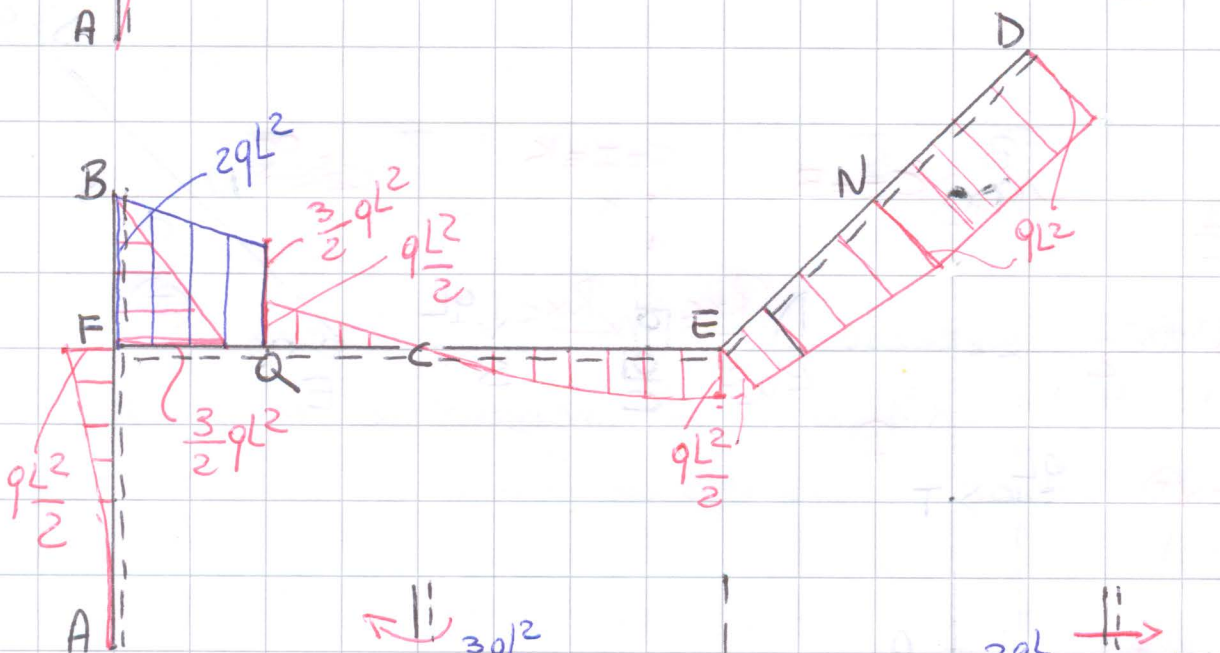
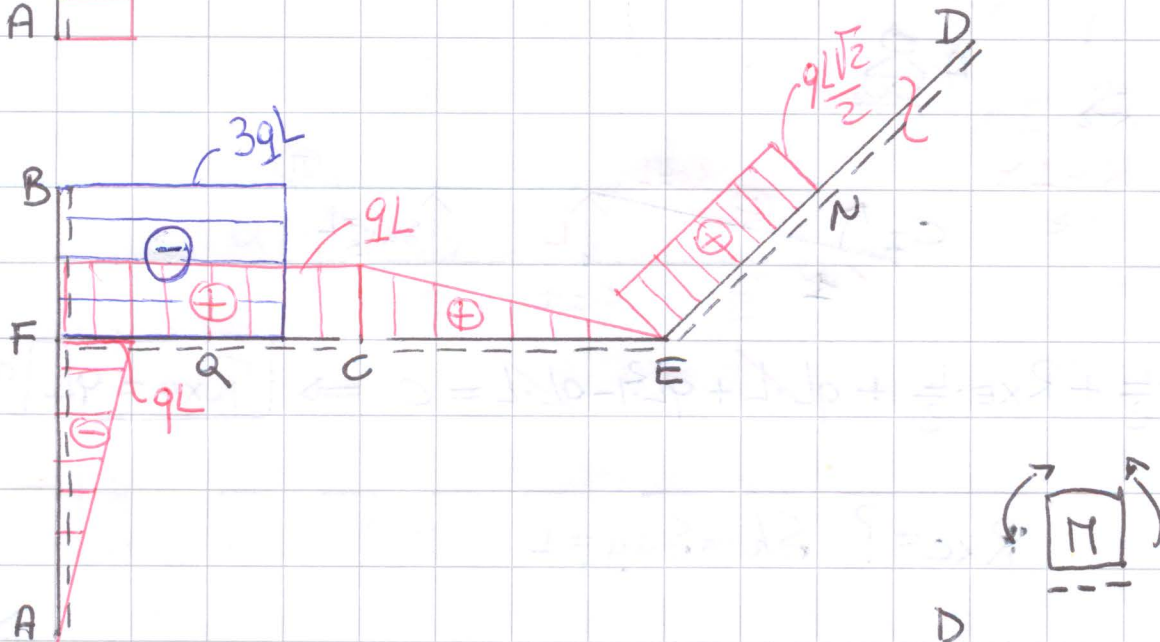
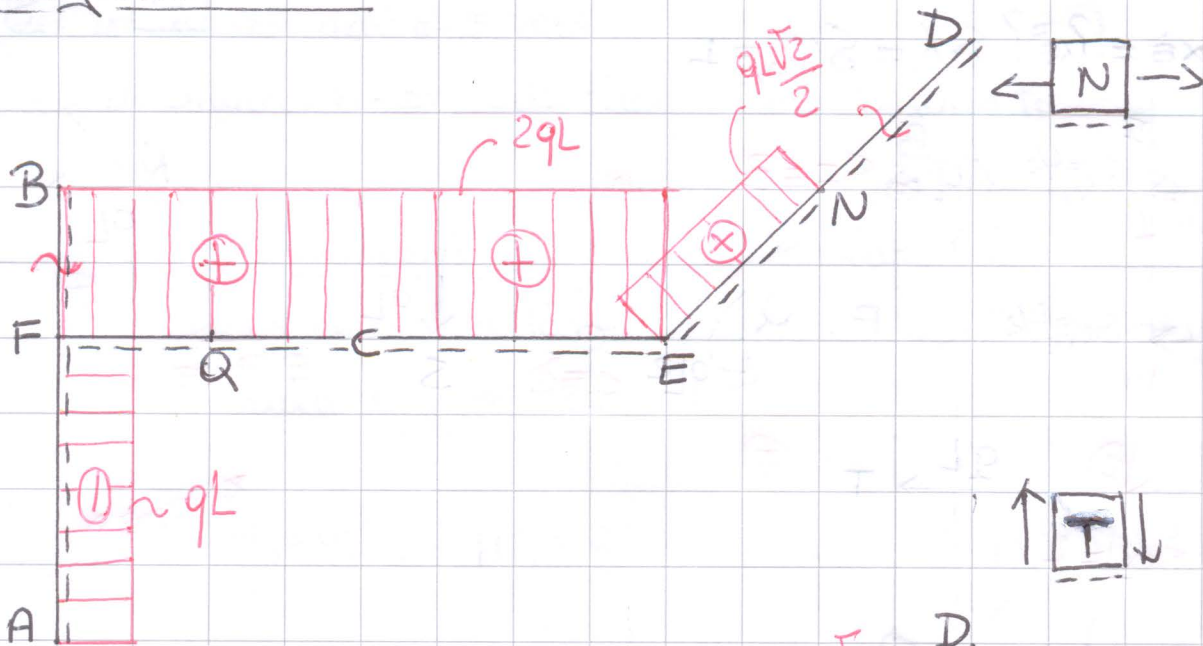
$$\sum M^{\text{II}}(C) = 0 \Rightarrow -qL^2 - qL^2 + M_D = 0 \Rightarrow M_D = qL^2$$

In definitiva si avrà:



Diagrammi CS

3



Verifica alle rotazioni nodo F

OK

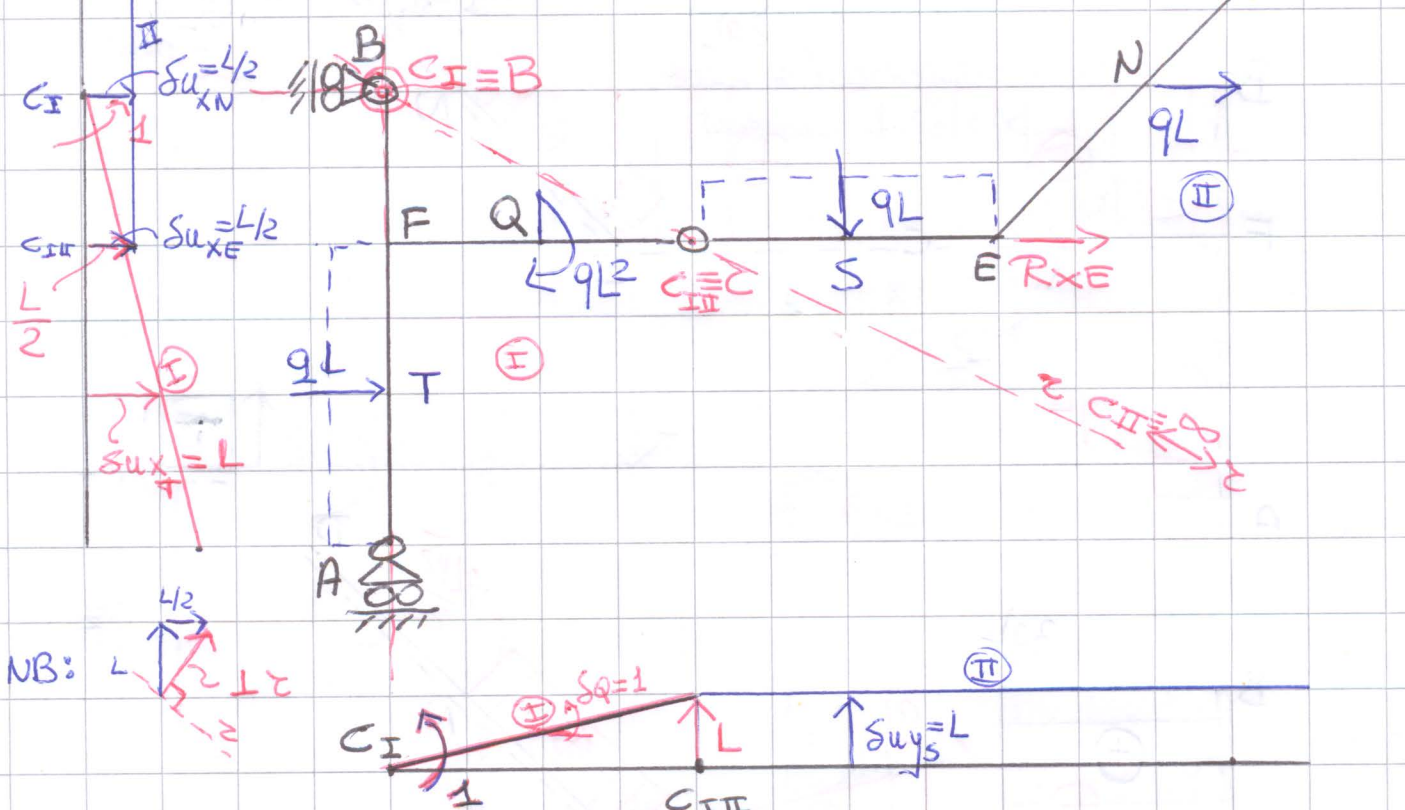
Verifica alla trasf. nodo F

OK

SOLUZIONE ES#2

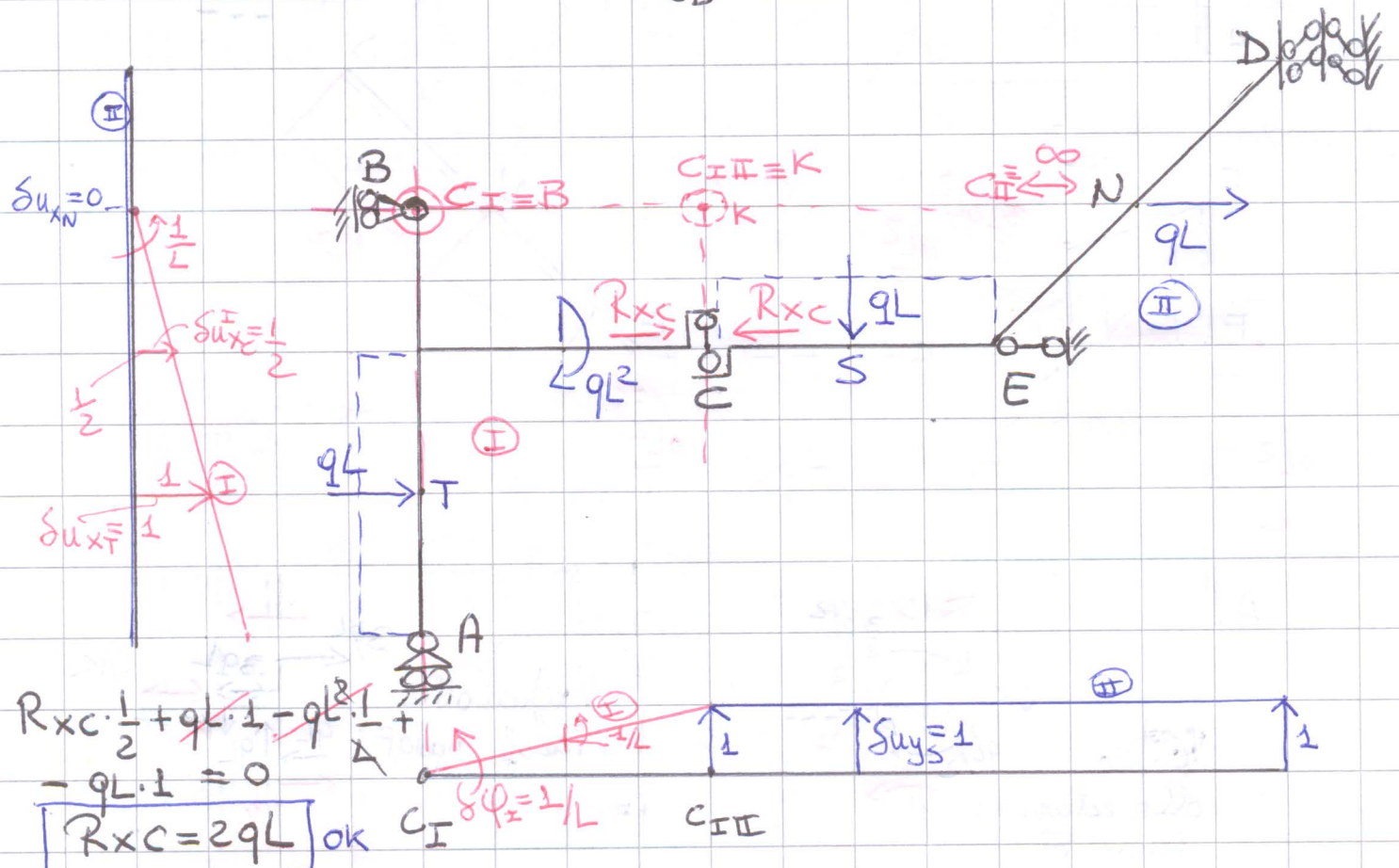
3

$R_{xE}=? \quad \delta h = \delta \varphi_B = 1$



$$qL \cdot \frac{L}{2} + R_{xE} \cdot \frac{L}{2} + qL \cdot L - qL^2 - qL \cdot L = 0 \Rightarrow R_{xE} = qL \text{ ok}$$

$R_{xC}=? \quad \delta h = \delta u_{yD} = 1$



$$R_{xC} \cdot \frac{1}{2} + qL \cdot 1 - qL \cdot \frac{1}{2} + qL \cdot 1 - qL \cdot 1 = 0 \Rightarrow R_{xC} = 2qL \text{ ok}$$